

EXPO Transfer Inquiry Details

Application No 10676155

Art Unit 2863

Class 702

Subclass 094000

☐ Classification☒ Transfer to GAU

Request by

LE, JOHN H (#78032)

Gau*

Class

use three digits for class

Subclass

Reason

Concurred by

(Examiner No.)

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Transfer History									
Transfer Inquiry	From GAU	To GAU	To Class	To Subclass	Requested By Decision By	Concurred By	Date	Reason	Status
		2863	702	094000	Docketed /		9/15/2004		
		2863	702	094000	Docketed /		7/9/2004		
Transfer to 2857	2613	2857	702	104	LEE, RICHARD J / 71286		5/22/2004	image sensor calibration system	C

L Number	Hits	Search Text	DB	Time stamp
-	1	10/676155	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/20 16:31
-	3	((image with sens\$3) same calibrat\$4 same (data parameter)) and (alignment same (image with sens\$3) same (geometric with axis) same vehicle)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/20 11:41
-	3	((image with sens\$3) same calibrat\$4 same (data parameter)) and (alignment same (image with sens\$3)) and ((geometric with axis) same vehicle)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/20 13:50
-	1	((((image with sens\$3) same calibrat\$4 same (data parameter)) and (alignment same (image with sens\$3))) and ((geometric with travel) same vehicle)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/20 12:24
-	6	((((image with sens\$3) same calibrat\$4 same (data parameter)) and (alignment same (image with sens\$3))) and (geometric same vehicle)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/20 13:00
-	59	702/\$.ccls. and ((image with sens\$3) same calibrat\$4 same (data parameter))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/21 13:38
-	6	(702/\$.ccls. and ((image with sens\$3) same calibrat\$4 same (data parameter))) and (alignment same (image with sens\$3))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/22 09:47
-	20	(702/\$.ccls. and ((image with sens\$3) same calibrat\$4 same (data parameter))) and (adjust\$6 same (image with sens\$3))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/20 13:49
-	5	((702/\$.ccls. and ((image with sens\$3) same calibrat\$4 same (data parameter))) and (adjust\$6 same (image with sens\$3))) and geometric and vehicle	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/21 19:11
-	2	EP-1120746-\$.did.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/21 15:40
-	4	702/\$.ccls. and ((image with sens\$3) same calibrat\$4 same (data parameter)) and (adjust\$6 with image with sens\$3) and vehicle	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/21 13:46
-	10	(image with sens\$3) same calibrat\$4 same (data parameter) and (adjust\$6 with image with sens\$3) and vehicle	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/21 14:39

-	3	((image with sens\$3) same calibrat\$4 same (data parameter) and (adjust\$6 with image with sens\$3) and vehicle) and geometric\$6	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/21 14:35
-	1	((adjust\$6 align\$6) with image with sens\$3) same (geometric\$6 with travel with vehicle)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/21 14:41
-	5	((adjust\$6 align\$6) with image with sens\$3) same (geometric\$6 with vehicle)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/21 15:40
-	1	((adjust\$6 align\$6) with image with sens\$3) and (geometric\$6 with vehicle with (travel\$6 or mov\$6))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/21 18:26
-	58	((adjust\$6 align\$6) with position with image with sens\$3) and (vehicle with (travel\$6 or mov\$6))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/21 15:51
-	3	((adjust\$6 align\$6) with position with image with sens\$3) and (vehicle with (travel\$6 or mov\$6))) and ((evalu\$6 estimat\$6) with image with data)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/21 15:43
-	15	((adjust\$6 align\$6) with position with ((image with sens\$3) or camera)) and (vehicle with (travel\$6 or mov\$6)) and ((evalu\$6 estimat\$6) with image with data)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/21 20:45
-	2	(geometric\$6 adj travel\$6 adj axis) and vehicle	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/21 18:27
-	1	(((geometric\$6 with travel\$6 with axis) and vehicle) and (image near2 sensor)) and ((align\$6 or adjust\$6) with position with (image near2 sensor))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/21 19:00
-	39	(((geometric\$6 with travel\$6 with axis) and vehicle) and (image near2 sensor)) and ((align\$6 or adjust\$6) with (image near2 sensor))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/21 18:31
-	41	(((geometric\$6 with travel\$6 with axis) and vehicle) and (image near2 sensor))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/21 18:32
-	5	((adjust\$6 align\$6) with position with ((image with sens\$3) or camera)) and (vehicle with (travel\$6 or mov\$6)) and ((evalu\$6 estimat\$6) with image with data) and (angle with measur\$6)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/21 18:35

-	2	(((geometric\$6 near2 (travel\$6 driv\$3) near2 axis) and vehicle) and (image near2 sensor)) and ((align\$6 or adjust\$6) with position with (image near2 sensor))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/21 19:01
-	3	(((geometric\$6 near2 (travel\$6 driv\$3) near2 axis) and vehicle) and (image near2 sensor)) and ((align\$6 or adjust\$6) with (image near2 sensor))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/21 19:01
-	1	(intrinsic with calibration with data) and (camera with principal with point) and (camera with principal with distance) and (distortion with parameter) and (glass with pane)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/21 20:49
-	1	(intrinsic with calibration with data) and (camera with principal with point) and (camera with principal with distance) and (glass with pane)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/21 20:48
-	1	(intrinsic with calibration with data) and (camera with principal with point) and (camera with principal with distance)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/21 20:48
-	1	(intrinsic with calibration with data) and (camera with point) and (camera with distance) and (distortion with parameter) and (glass with pane)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/21 20:50
-	1	(intrinsic with calibration with data) and (camera with point) and (camera with distance) and (distortion with parameter) and glass	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/21 20:50
-	11	("4152061" "4236794" "4789940" "4954962" "5036474" "5101277" "5170352" "5307170" "5400383" "5453845" "5460312").PN.	USPAT	2004/09/22 09:42
-	0	((("4152061" "4236794" "4789940" "4954962" "5036474" "5101277" "5170352" "5307170" "5400383" "5453845" "5460312").PN.) and (glass near2 pane)	USPAT	2004/09/22 09:47
-	0	((("4152061" "4236794" "4789940" "4954962" "5036474" "5101277" "5170352" "5307170" "5400383" "5453845" "5460312").PN.) and (influence with glass)	USPAT	2004/09/22 09:48
-	4	("4692806" "5134473" "5270756" "5296926").PN.	USPAT	2004/09/22 09:44
-	0	((("4692806" "5134473" "5270756" "5296926").PN.) and (glass near2 pane)	USPAT	2004/09/22 09:44
-	0	((("4692806" "5134473" "5270756" "5296926").PN.) and (influence with glass)	USPAT	2004/09/22 09:44
-	7	("5068791" "5247487" "5949685" "6047234" "6226571" "6275773" "6292752").PN.	USPAT	2004/09/22 09:47
-	0	((("5068791" "5247487" "5949685" "6047234" "6226571" "6275773" "6292752").PN.) and (glass near2 pane)	USPAT	2004/09/22 09:48
-	0	((("5068791" "5247487" "5949685" "6047234" "6226571" "6275773" "6292752").PN.) and (influence with glass)	USPAT	2004/09/22 09:48